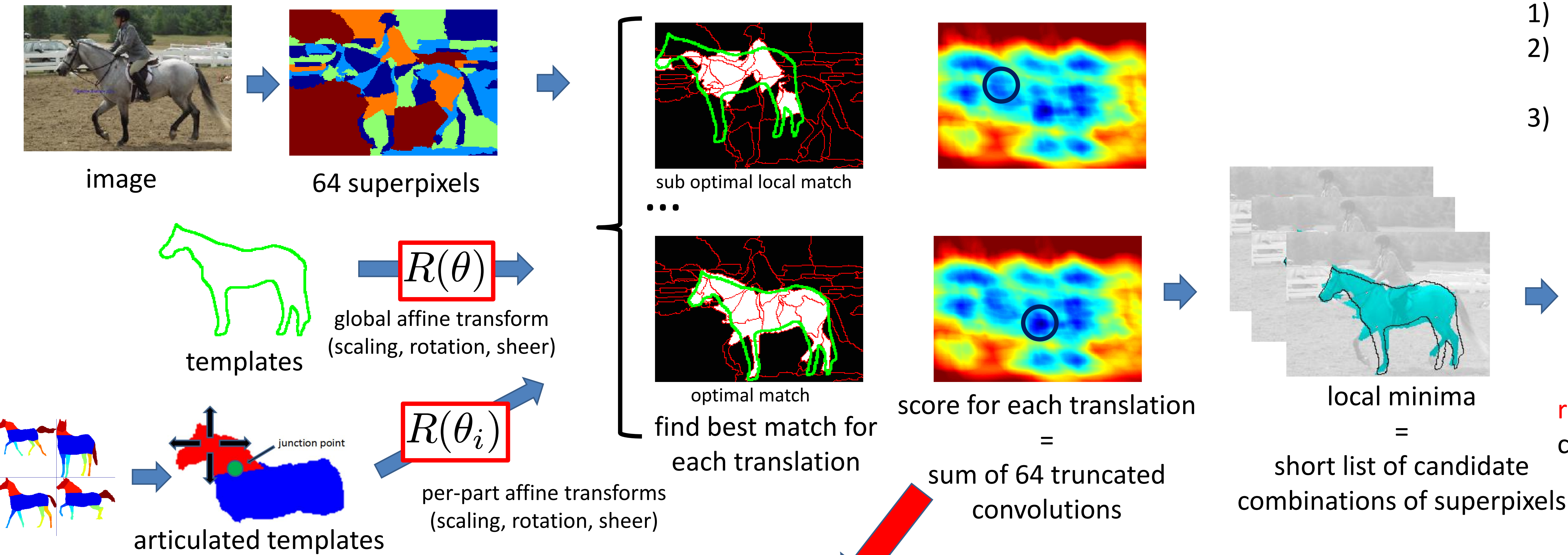


**Goal:** object specific segmentation given a few hand-segmented images of that category

**Main challenge:** integrate **bottom-up** segmentation cues with **top-down** model cues

**Our approach:** exhaustive search in the space of **superpixel combinations** with **separable** cost function



**Contribution:** **efficient** shape detection/segmentation based on 3 ideas:

- 1) exhaustive search over superpixel combinations can be **decoupled**
- 2) a **discrete version of Green's theorem** is used to compute the correlation score
- 3) **coarse to fine scheme** (with conditions for optimality) allows for linear time detection

**space complexity:**  $O(|\partial Y|)$  using compression based on *Run Length Encoding*  
 $\Rightarrow$  8,000 large templates fit in 2MB

**time complexity:**  $O(|\partial Y|)$  per translation using Green's theorem, and  $O(npixels)$  per template across translations using coarse to fine  
 $\Rightarrow$  0.01 seconds per template

## Cost Function for Shape Detection and Segmentation

shape distance function:  
*invariant to similarity transforms*

$$d(X, Y) = \min_{T \in \mathbb{T}} \frac{1}{|T(Y)|} d_H(X, T(Y))$$

mask, template, affine transform, Hamming distance

$$\text{cost function: } \epsilon(Y) = \min_{S \subset [1, \dots, k]} d(R_S, Y)$$

search space:  
 $2^{64}$  possibilities !!  
 subset of superpixels, template

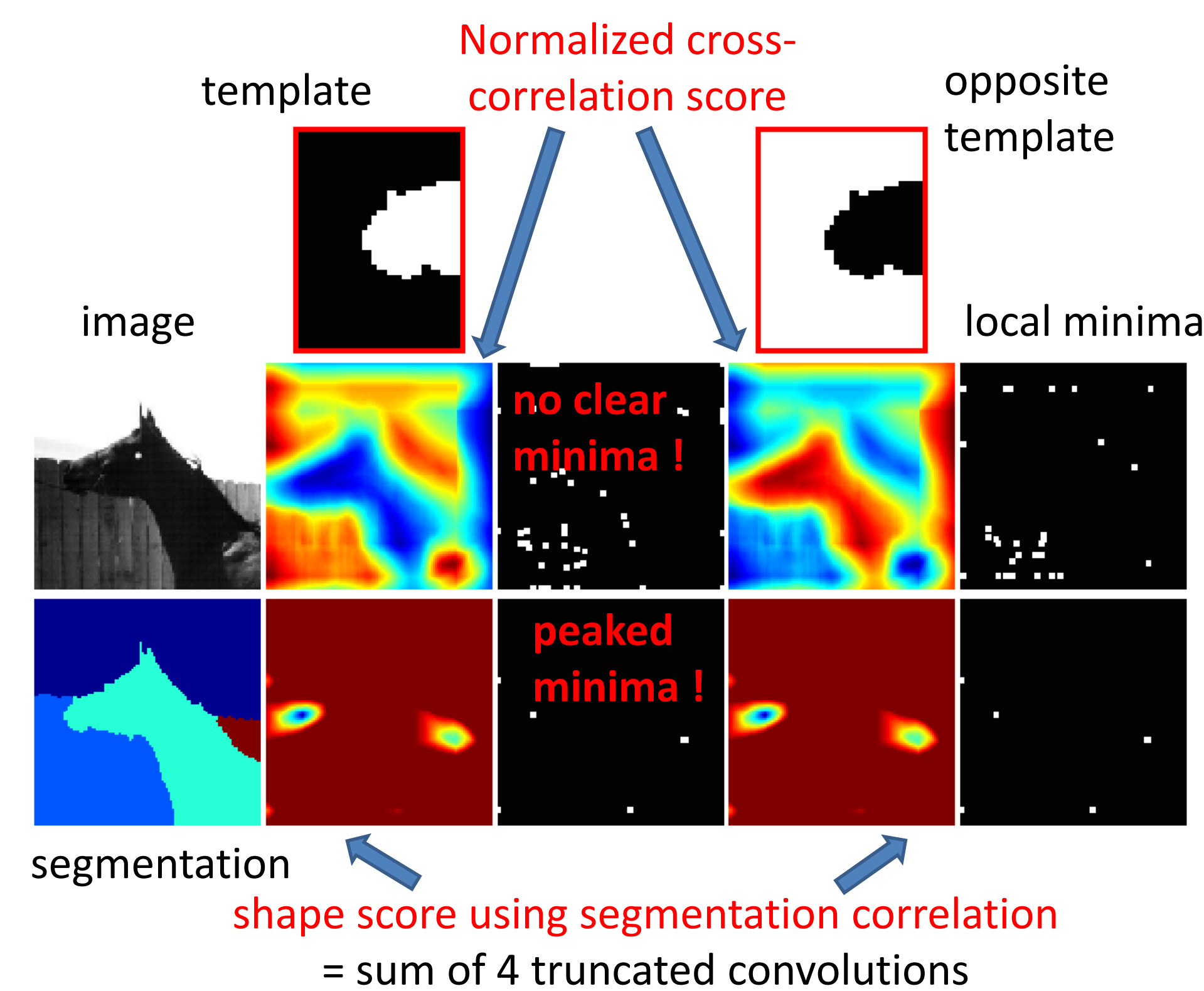
cost can be decoupled w.r.t. each region  $R_j$ :  $\epsilon(y) = 1 + \min_{T \in \mathbb{T}} \frac{1}{|T(y)|^2} \sum_j \sigma_j(T(y))$

as a sum of truncated convolutions  $\sigma_j(y) = \min(0, |R_j| - 2r_j^T y)$

region with  $r_j^T y > \frac{1}{2}|R_j|$

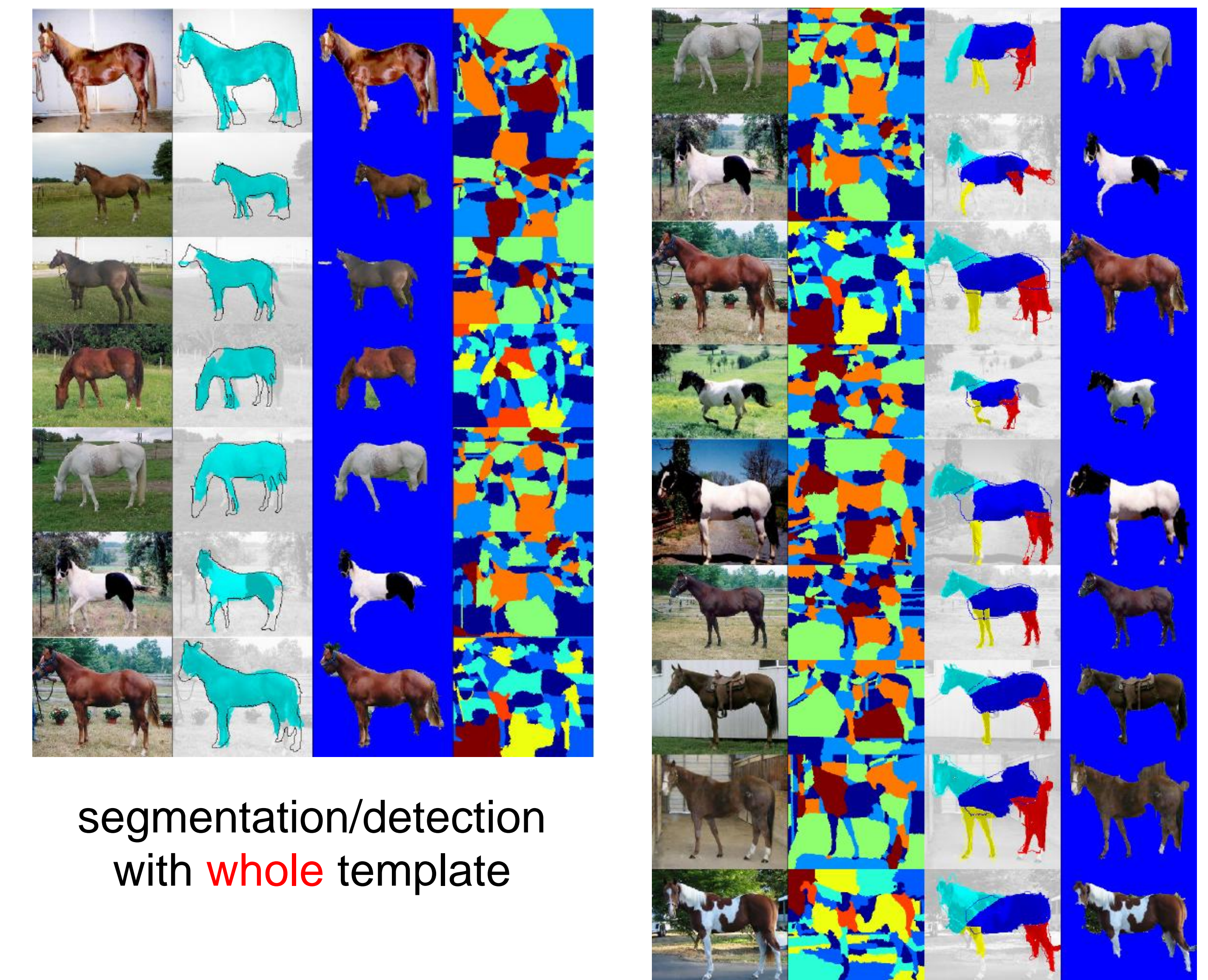
gray-level correlation  
 vs. segmentation correlation

gray level correlation (or NCC) is very sensitive to variations in illumination of both foreground and background



## Results on Weizmann horse dataset

training/testing: 20/308 images  
 average pixel consistency: **94.2%** (using the oracle best out of 10)  
 same with articulated model: **95.2%** (using the oracle best out of 10 for each part)



segmentation/detection with **whole** template

segmentation/detection with **articulated** template

how to detect a template anywhere in a large image in  $O(npixels)$  or 0.01 seconds

**discrete version of Green's theorem** for fast *random-access* convolution

$$\text{Image region } R_j * \text{Template } y = \text{signed region boundary} * \text{Integral Template } \mathbf{I}_u y$$

**sparse!**

$$\text{for each region } R_j \quad r_j^T y = \iint_{R_j} y = \iint_{R_j} \frac{\partial \mathbf{I}_u y}{\partial u} = \int_{\partial R_j} \mathbf{I}_u y$$

running time per dot product:  $O(|\partial Y|)$  instead of  $O(|Y|)$

can be coupled with **coarse-to-fine approach** starting from the local maxima of the score at a coarser resolution projected on the fine resolution.

**NOT possible with FFT**, which is global!